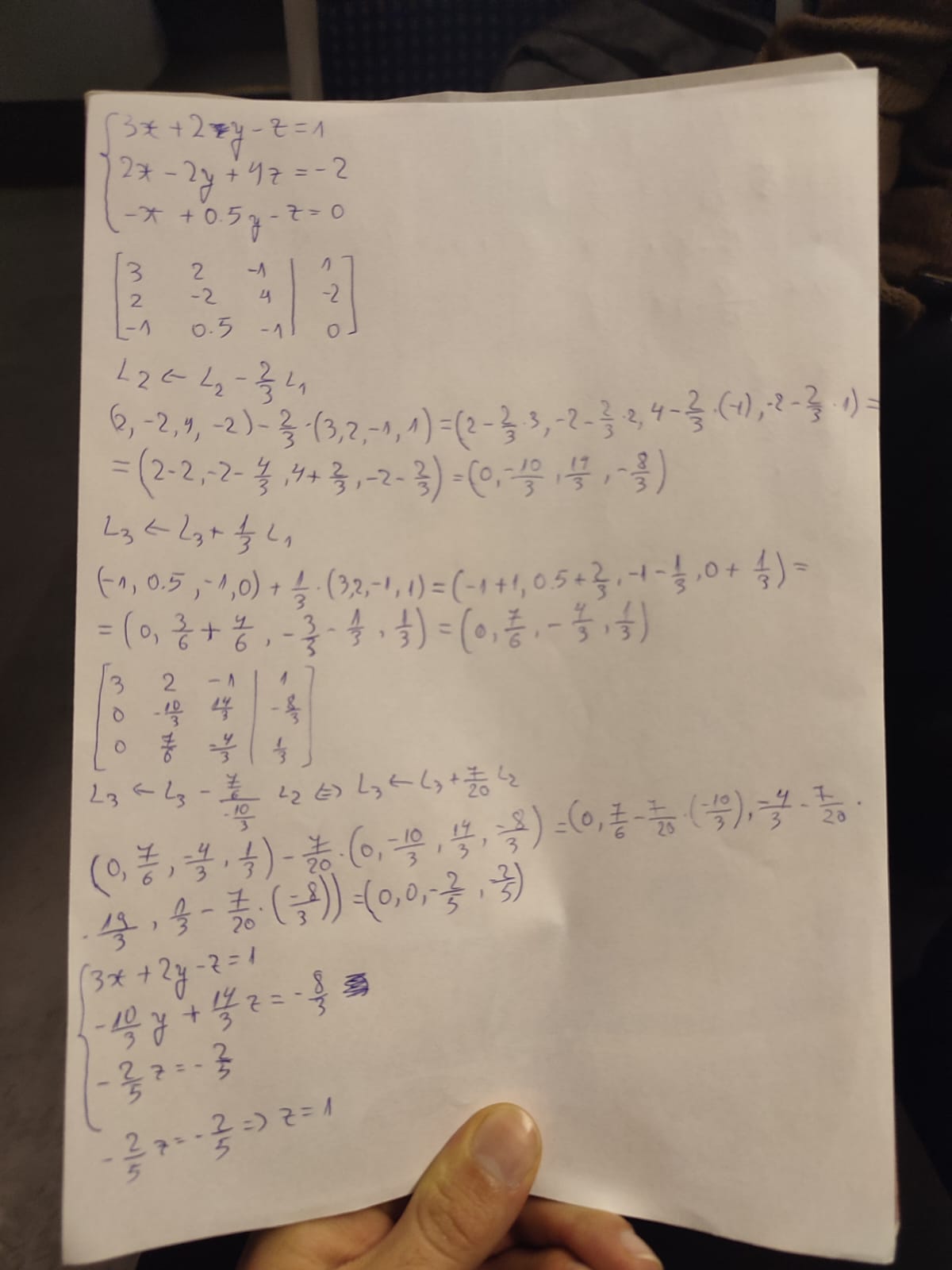
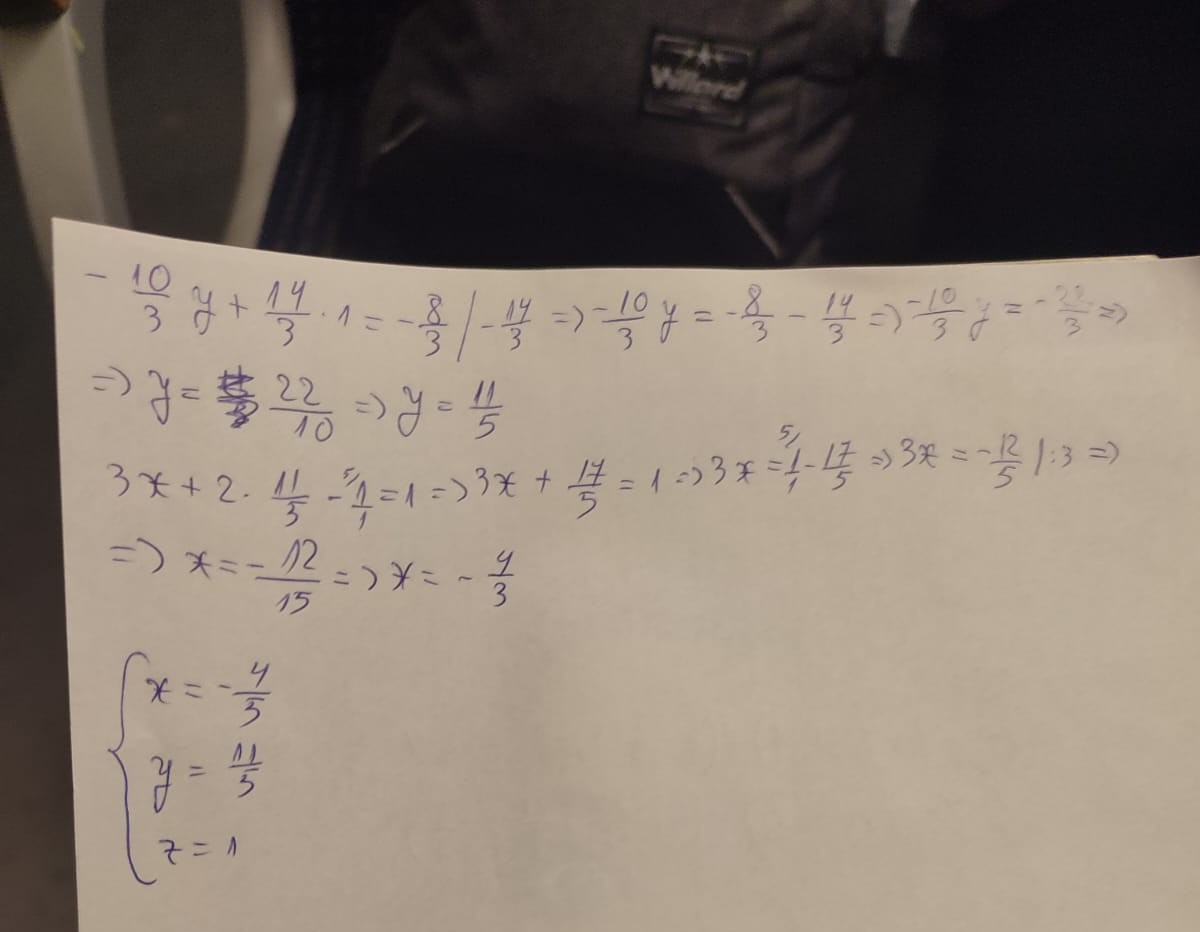
**Mocanu Marian Valentin** Tema Laborator 3+4









function x=rezolvare\_sistem()

A=[3 2 -1; 2 -2 4; -1 0.5 -1];

b=[1; -2; 0];

% aplicam eliminarea Gauss

Ab=[A b]; % matricea extinsa

n=length(b);

% faza de eliminare

for i=1:n-1

for j=i+1:n

m=Ab(j,i)/Ab(i,i);

Ab(j,:)=Ab(j,:)-m\*Ab(i,:);

end

end

% substitutia inversa

x=zeros(n,1);

for i=n:-1:1

x(i)=(Ab(i,end)-Ab(i,i+1:n)\*x(i+1:n))/Ab(i,i);

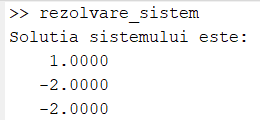
end

% afisam solutia

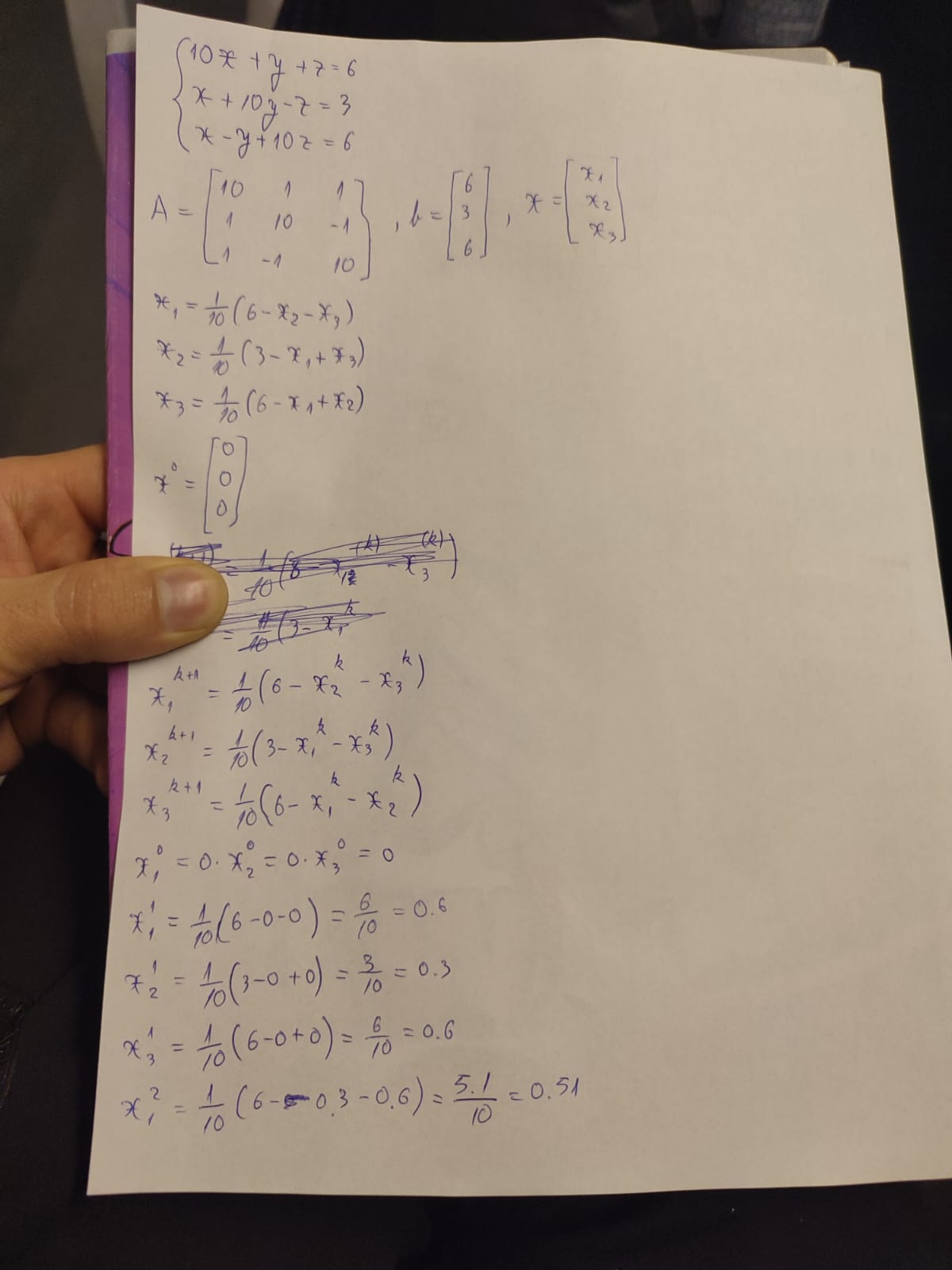
disp('Solutia sistemului este:');

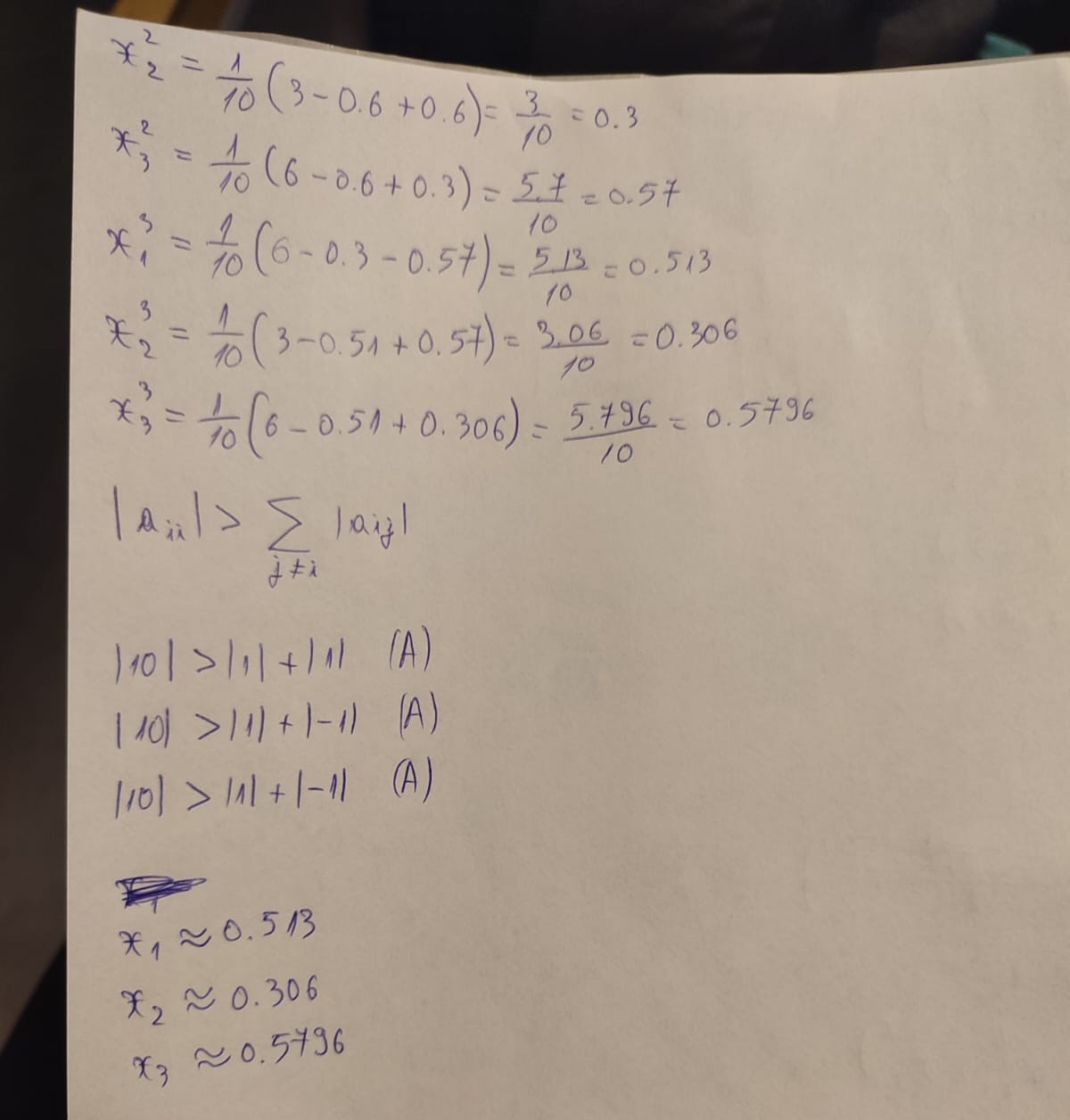
disp(x);

end









* jacobi\_method.m

function [X, iter]=jacobi\_method(A, B, X0, eps\_sis, Nmax)

if nargin < 5

error('Nu sunt suficienti parametri de intrare: "jacobi\_method(A, B, X0, eps\_sis, Nmax)"');

end

n=size(A,1);

if size(A,2)~=n || size(B,1)~=n || numel(B)~=n || numel(X0)~=n

error('Nepotrivire dimensionala: Asigura-te ca A este o matrice patrata, iar B și X0 sunt vectori coloana de dimensiune corespunzatoare.');

end

X=X0(:);

X\_prev=X;

iter=0;

while iter<Nmax

X\_new=X;

for i=1:n

sigma=A(i, :)\*X\_prev-A(i, i)\*X\_prev(i);

X\_new(i)=(B(i)-sigma)/A(i, i);

end

if norm(X\_new-X\_prev, inf)<eps\_sis

X=X\_new;

break;

end

X\_prev=X\_new;

iter=iter + 1;

end

X=X\_prev;

end

* ex2\_punctul\_b.m

A=[10 1 1; 1 10 -1; -1 1 10];

B=[6; 3; 6];

% alegem un vector initial X0

X0=zeros(size(B));

% definim precizia si numarul maxim de iteratii

eps\_sis=1e-6;

Nmax=5000;

% apelam functia

[X, iter] = jacobi\_method(A, B, X0, eps\_sis, Nmax);

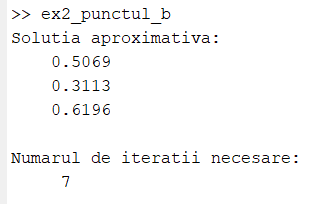
% afisam rezultatele

disp('Solutia aproximativa:')

disp(X)

disp('Numarul de iteratii necesare:')

disp(iter)





* generate\_test\_data.m

function [A, B, X\_exact]=generate\_test\_data(n)

% generam aleator o matrice patratica cu diagonala dominanta

A=rand(n)\*10;

for i=1:n

A(i, i)=sum(abs(A(i, :)))+rand()\*10;

end

% generam aleator un vector solutie exacta X\_exact

X\_exact=rand(n, 1)\*10;

% calculam vectorul B ca produs A\*X\_exact

B=A\*X\_exact;

end

* ex2\_punctul\_c.m

% setam dimensiunea sistemului

n=3;

% generam datele de test

[A, B, X\_exact]=generate\_test\_data(n);

% alegem o solutie initială X0

X0=zeros(n, 1);

% definim precizia si numarul maxim de iteratii

eps\_sis=1e-6;

Nmax=5000;

% apelam metoda Jacobi

[X\_approx, iter]=jacobi\_method(A, B, X0, eps\_sis, Nmax);

% afisam rezultatele

disp('Matricea A:')

disp(A)

disp('Vectorul B:')

disp(B)

disp('Solutia exacta X\_exact:')

disp(X\_exact)

disp('Solutia aproximativa obtinuta X\_approx:')

disp(X\_approx)

disp('Numarul de iteratii necesare:')

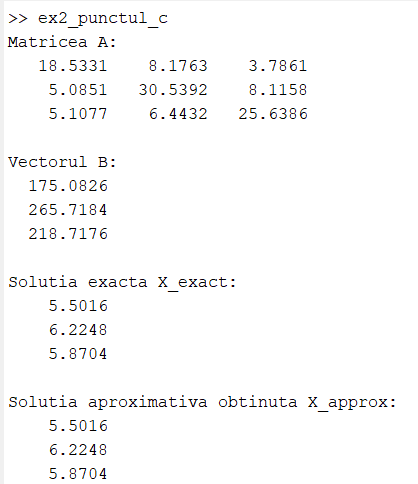
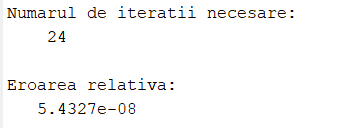
disp(iter)

% calculam eroarea relativa

error\_relative=norm(X\_approx - X\_exact, inf)/norm(X\_exact, inf);

disp('Eroarea relativa:')

disp(error\_relative)



* evaluate\_jacobi.m

function evaluate\_jacobi(n, eps\_sis, Nmax)

[A, B, X\_exact]=generate\_test\_data(n);

X0=zeros(n, 1);

[X\_approx, iter]=jacobi\_method(A, B, X0, eps\_sis, Nmax);

error\_relative=norm(X\_approx - X\_exact, inf)/norm(X\_exact, inf);

disp('Matricea A:');

disp(A);

disp('Vectorul B:');

disp(B);

disp('Soluția exactă X\_exact:');

disp(X\_exact);

disp('Soluția aproximativă X\_approx:');

disp(X\_approx);

disp('Numărul de iterații necesare:');

disp(iter);

disp('Eroarea relativă:');

disp(error\_relative);

end

* ex2\_punctul\_d.m

% setam dimensiunea sistemului

n=3;

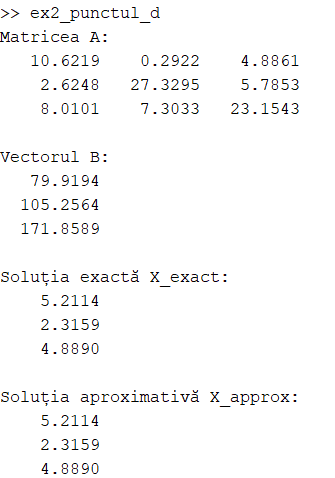
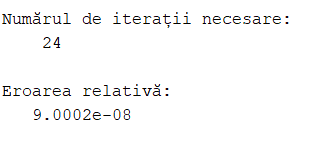
% definim precizia si numarul maxim de iteratii

eps\_sis=1e-6;

Nmax=5000;

% apelam functia de evaluare

evaluate\_jacobi(n, eps\_sis, Nmax);



* plot\_iterations\_vs\_precision.m

function plot\_iterations\_vs\_precision(n, Nmax)

eps\_values=logspace(-1, -16, 10);

iterations=zeros(size(eps\_values));

for i=1:length(eps\_values)

eps\_sis=eps\_values(i);

[A, B, ~]=generate\_test\_data(n);

X0=zeros(n, 1);

[~, iter]=jacobi\_method(A, B, X0, eps\_sis, Nmax);

iterations(i)=iter;

end

figure;

semilogx(eps\_values, iterations,'-o');

xlabel('Precizia');

ylabel('Numarul de iteratii');

title('Variatia numarului de iteratii in functie de precizie');

grid on;

end

* ex2\_punctul\_e.m

% setam dimensiunea sistemului si numarul maxim de iteratii

n=3;

Nmax=5000;

% apelam functia pentru a genera graficul

plot\_iterations\_vs\_precision(n, Nmax);

